



COMSAC SYMPOSIUM

Introductory Remarks

September 23, 2003

Dr. Darrel R. Tenney

Director for Aerospace Vehicle Systems Technology Office NASA Langley Research Center Hampton, VA



NASA/DoD Aerodynamic Flight Prediction Workshop



Nov. 19-21, 2002 in Williamsburg, VA



Tim Naumomicz

Dan Murri Dave Evans Brian Lundy
Pradeep Raj Lawrence Ash Mike Hemsch
Sie Cook Brian Kgamer
Rich Walshighm Rudowsky Ed KraffMike Fremau/Boe Chambers Frank Lynch
Pradeep Raj Lawrence Ash Mike Hemsch
Bill Baker
Sue Crotts
Terry Britt Ajay Kumar
Donna Speller
Long Yip
Hugo Gonzales
Greg Addington
Roger Clark

Steve Cook Brian Kgamer
Rich Walshighm Rudowsky Ed KraffMike Fremau/Boe Chambers Frank Lynch
Mark Potadam Mark BooherJohn Rundquist Jim Thomas
Bill Sellers John Malone
Frank Berrier Tom Lawrence
Bill Sellers John Liughton
Bill Sellers John Li

2



General Findings

Aerodynamic Flight Prediction Workshop

Nov. 19-21, 2002 in Williamsburg, VA





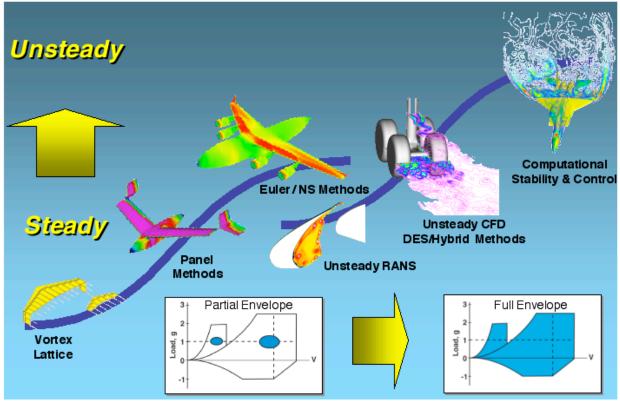


- 1. Prediction of the onset of separated flows across the speed range (with the attendant issues of transition prediction, turbulence modeling, unsteady flows, etc.) and the character and impact of separated flow on aircraft capabilities is the single most critical fundamental issue to be addressed and should receive a very high priority in aerodynamic R&D programs.
- 2. The issue of Reynolds number impacts on aerodynamic predictions continues to pose significant barriers to advances in the state of the art. The issues leading to this situation (cost, accuracies, operational difficulties, etc.) should be addressed with high priority.
- loss of corporate knowledge documentation of lessons learned in aerodynamic predictions is a major area of concern. As a result of corporate mergers, large tumovers in staffs within government and industry, and fewer aircraft programs, the nation is rapidly losing its cornerstone experience base for the future.

3









Concluding Remarks



- · Future vehicle designs will see a paradigm shift from
 - Steady to the unsteady world (e.g. flow control, adaptive morphing),
 - Passive to active.
 - Rigid designs to exploitation of flexibility and adaptability
 - Few discrete to numerous distributed (e.g. sensors, control surfaces)
 - To obtain a vehicle that is always at optimum performance.
- Therefore, future designs will be inherently multidisciplinary, and the greatest technical challenges and opportunities occur at the intersection of disciplines
- COMSAC appears to be a step towards enabling the future vision